

M-410iC/315 (Hollow wrist)



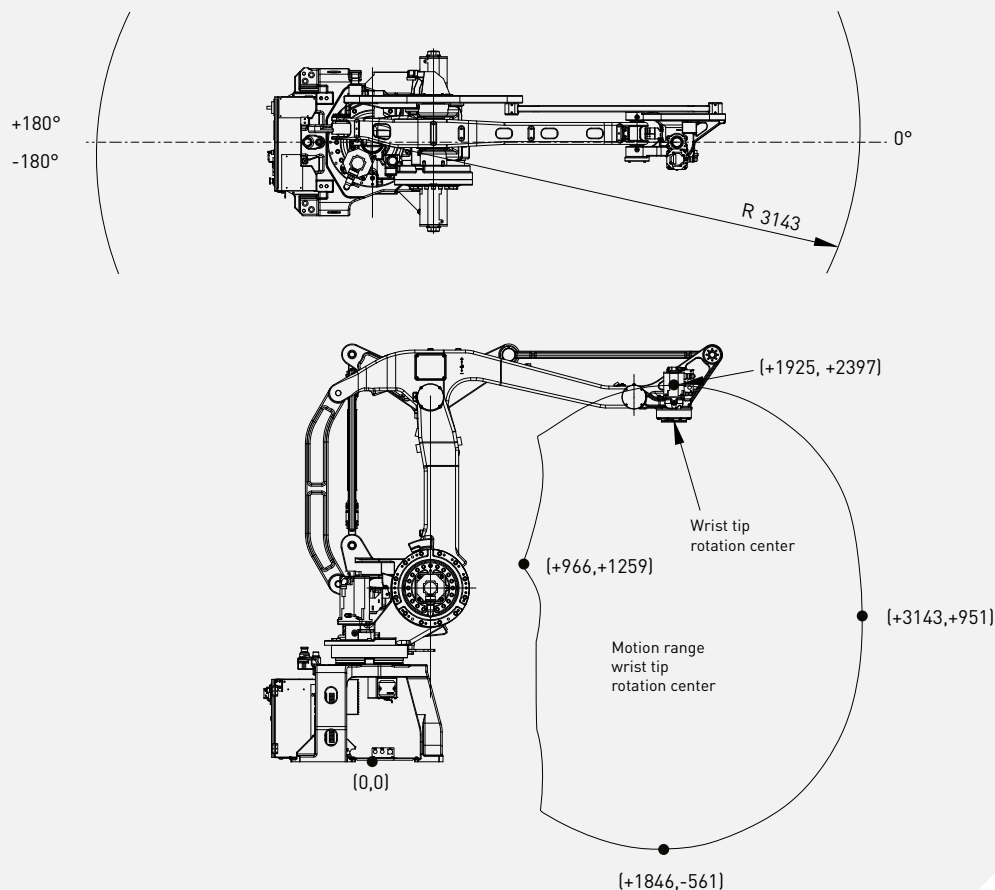
Max. load capacity
at wrist: **315 kg**



Max. Reach:
3143 mm

Controlled axes	Repeatability (mm)	Mechanical weight (kg)	Motion range [°]						Maximum speed [°/s]						J4 Moment/ Inertia (Nm/kgm²)	J5 Moment/ Inertia (Nm/kgm²)	J6 Moment/ Inertia (Nm/kgm²)
			J1	J2	J3	J4	J5	J6	J1	J2	J3	J4	J5	J6			
4	± 0.5	1600 (1330)	360	144	136	720	–	–	90	100	110	195	–	–	155	–	–

Working Range



Robot

	M-410iC/315
Robot footprint [mm]	1094 x 945 (806 x 610)
Mounting position Floor	●
Mounting position Upside down	-
Mounting position Angle	-



Controller

	30iB
Open air cabinet	-
Mate cabinet	-
A-cabinet	●
B-cabinet	○
iPendant Touch	●

Electrical connections

Voltage 50/60Hz 3phase [V]	380-575
Voltage 50/60Hz 1phase [V]	-
Average power consumption [kW]	1

Integrated services

Integrated signals on upper arm In/Out	8/8
Integrated air supply	1

Environment

Acoustic noise level [dB]	< 70
Ambient temperature [° C]	0-45

Protection

Body standard/optional	IP54 /IP55
Wrist & J3 arm standard/optional	IP67

● standard ○ on request - not available [] with hardware and/or software option